Lego Robotics Camp

Day 2: Conditionals and Loops



Review

- Yesterday we:
 - Engaged with the four pillars of computational thinking
 - Designed algorithms for simple tasks (PB&J, robot dancing)
 - Got acquainted with our robots and programming environment
 - Learned about variables (names for specific objects in our programs)







Today's Plan

- Today we will:
 - Learn about **conditionals** and **loops**
 - Design simple algorithms for parking our robots



Simon Jeannie Says...



Conditional Statements

- If (you were born in the winter) then (touch your head)
 Else (clap your hands)
- If (you play the trumpet) then (jump up and down 3 times)
 Else (spin in a circle)
- If (your favorite ice cream flavor is chocolate) then (clap your hands)
 Else if (your favorite ice cream flavor is vanilla) then (touch your toes)
 Else (sit on the floor)
- If (some condition is true) then (do some action)
 Else if (some other condition is true) then (do some other action)
 Else (do some other different action)

Conditional Statements

- True and false are called **boolean** values
- If-else (or conditional) statements require checking if a boolean condition is true or false and responding appropriately
- In Python:



Python example

a = 200

- b = 33
- if b > a:

```
print("b is greater than a")
```

elif a > b:

print("a is greater than b")

else:

```
print("a is equal to b")
```











```
if condition1 is true:
       Python example
                                              do action 1
                                        elif condition2 is true:
                                             do action 2
                                        else:
a = 33
                                             do action 3
b = 33
if b > a:
 print("b is greater than a")
elif a > b<mark>:</mark>
print("a is greater than b")
else<mark>:</mark>
                                        Note that punctuation and
 print("a is equal to b")
                                        indentation matter A LOT!
```

- Suppose we want to design a simple algorithm for walking in a perfect square around the room
 - Start and end at same spot
 - Remember pillars of computational thinking (decomposition, pattern recognition, abstraction, algorithms)



- Suppose we want to design a simple algorithm for walking in a perfect square around the room
 - Walk forward 10 steps
 - Turn left 90 degrees
 - Walk forward 10 steps
 - Turn left 90 degrees
 - Walk forward 10 steps
 - Turn left 90 degrees
 - Walk forward 10 steps
 - Turn left 90 degrees



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How can this be simplified?

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How can this be simplified?

Which lines are repeated?

- Suppose we want to design a simple algorithm for walking in a perfect square around the room
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How can this be simplified?

Which lines are repeated?

How many times are they repeated?

- Suppose we want to design a simple algorithm for walking in a perfect square around the room
 - Repeat 4 times:
 - Walk forward 10 steps
 - Turn left 90 degrees
 - This is called a loop
 - Simplifies and shortens repeated code



Robot Example

robot.straight(500)
robot.turn(90)
robot.straight(500)
robot.turn(90)
robot.straight(500)
robot.turn(90)
robot.straight(500)
robot.straight(500)

Robot Example

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robot.straight(500)
robot.turn(90)

num_turns = 0; while num_turns < 4: robot.straight(500) robot.turn(90) num_turns = num_turns+1

Loops

- While condition is true:
 - Do some action repeatedly
- If condition never becomes false, the loop will go on forever!
- This is called an **infinite loop**
- In Python, loops look like:





Python example



Python example





Python example



Python Quiz



Python Quiz





Hard Python Quiz What will this print? a = 1 b = 52 3 c = 3we are here while a < b: 4 print(a) if a == c: print("we are here!") a = a + 1

Summary

- Conditionals and loops allow us to solve much more interesting problems with our robots
- Tomorrow we'll look at some examples



Parking Algorithms

- Yesterday we made our robots move
- Today we'll examine algorithms for parking your robots
- We won't need conditionals or loops (yet)
- The goal of today's lab is to gain more experience with moving and turning our robots
- What are common parking scenarios?

Parking Algorithms

- Yesterday we made our robots move
- Today we'll examine algorithms for parking your robots
- We won't need conditionals or loops (yet)
- The goal of today's lab is to gain more experience with moving and turning our robots
- What are common parking scenarios?
 - Perpendicular parking
 - Parallel parking

Perpendicular Parking

• Bad examples:



Perpendicular Parking

 Park in spaces that are perpendicular (90 degrees) away from your car's straight line motion



Think Pair Share

- Work with a partner to develop your own algorithm for perpendicular parking your robots!
- You aren't writing actual code (yet!)
- You are thinking about the logical steps
- Example:
 - Move forward 500 cm
 - Turn 90 degrees clockwise
 - Move backward 500 cm
 - Turn 60 degrees counter-clockwise

Challenges

- Why was this hard?
- What information did you need to write this algorithm?
- Suppose we want to make our robots *autonomous* (selfdriving). How would this work for your parking algorithm?

 First, let's look at an example of a bad algorithm



Here's a good algorithm





• One more using EV3 robots



Think Pair Share

- Work with a partner to develop your own algorithm for parallel parking your robots
- You still aren't writing actual code (yet!)
- You are thinking about the logical steps
- Example:
 - Move forward 500 cm
 - Turn 90 degrees clockwise
 - Move backward 500 cm
 - Turn 60 degrees counter-clockwise

Self-Driving Cars

- Let's extend this idea a bit and think about self-driving cars
- What decisions do cars have to make when parking?
- What other decisions to cars make when driving?
- How do self-driving cars work?

Lab

- For lab today, you will write code for parking your robots
- Start with perpendicular, then try parallel
- You can create your own practice course
- But you have to pass my test to get your license!
- Think about what it would take to make your robot autonomous with respect to parking.



LUNCH BREAK